



# Detecting stochastic inclusions in electrical impedance tomography

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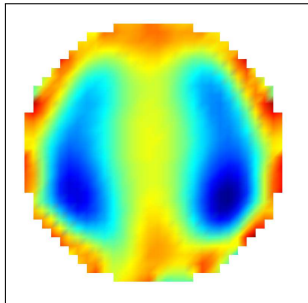
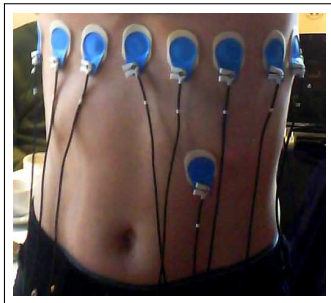
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(joint work with A. Barth, N. Hyvönen and L. Mustonen)

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## Electrical impedance tomography (EIT)



- ▶ Apply electric currents on subject's boundary
- ▶ Measure necessary voltages
- ↪ Reconstruct conductivity inside subject.



## Mathematical Model (deterministic)

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Electrical potential  $u(x)$  solves

$$\nabla \cdot (\sigma(x) \nabla u(x)) = 0 \quad x \in D$$

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$D \subset \mathbb{R}^n$ : imaged body,  $n \geq 2$

$\sigma(x)$ : conductivity

$u(x)$ : electrical potential

Idealistic model for boundary measurements (continuum model):

$\sigma \partial_\nu u(x)|_{\partial D}$ : applied electric current

$u(x)|_{\partial D}$ : measured boundary voltage (potential)

## Calderón problem (deterministic)

Can we recover  $\sigma \in L_+^\infty(D)$  in

$$\nabla \cdot (\sigma \nabla u) = 0, \quad x \in D \quad (1)$$

from all possible Dirichlet and Neumann boundary values

$$\{(u|_{\partial D}, \sigma \partial_\nu u|_{\partial D}) : u \text{ solves (1)}\}?$$

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Equivalent: Recover  $\sigma$  from **Neumann-to-Dirichlet-Operator**

$$\Lambda(\sigma) : L_\diamond^2(\partial D) \rightarrow L_\diamond^2(\partial D), \quad g \mapsto u|_{\partial D},$$

where  $u$  solves (1) with  $\sigma \partial_\nu u|_{\partial D} = g$ .

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## Inclusion detection in EIT

- $\sigma$ : Actual (unknown) conductivity
- $\sigma_0$ : Initial guess or reference state (e.g. exhaled state)
  - ▶  $\text{supp}(\sigma - \sigma_0)$  often relevant in practice

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**Inclusion detection problem** (aka shape reconstruction or anomaly detection)

*Can we recover  $\text{supp}(\sigma - \sigma_0)$  from  $\Lambda(\sigma), \Lambda(\sigma_0)$ ?*

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- ▶ Generic approach: parametrize  $\text{supp}(\sigma - \sigma_0)$ , Level-Set-Methods
- ▶ Problems:
  - ▶ PDE solutions required in each iteration
  - ▶ convergence unclear



## Linearization and inclusion detection

**Theorem** (H./Seo, SIAM J. Math. Anal. 2010)

Let  $\kappa, \sigma, \sigma_0$  pcw. analytic.

$$\Lambda'(\sigma_0)\kappa = \Lambda(\sigma) - \Lambda(\sigma_0) \implies \text{supp}_{\partial D}\kappa = \text{supp}_{\partial D}(\sigma - \sigma_0)$$

$\text{supp}_{\partial D}$ : outer support ( = supp + parts unreachable from  $\partial D$  )

- ↪ Inclusion detection is essentially a linear problem.
- ↪ Fast, rigorous and globally convergent inclusion detection methods are possible.
- ▶ **Next slides:** Monotonicity method.

# Monotonicity

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For two conductivities  $\sigma_0, \sigma_1 \in L^\infty(\Omega)$ :

$$\sigma_0 \leq \sigma_1 \implies \Lambda(\sigma_0) \geq \Lambda(\sigma_1)$$

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This follows from

$$\int_{\Omega} (\sigma_1 - \sigma_0) |\nabla u_0|^2 \geq \int_{\partial\Omega} g (\Lambda(\sigma_0) - \Lambda(\sigma_1)) g \geq \int_{\Omega} \frac{\sigma_0}{\sigma_1} (\sigma_1 - \sigma_0) |\nabla u_0|^2$$

for all solutions  $u_0$  of

$$\nabla \cdot (\sigma_0 \nabla u_0) = 0, \quad \sigma_0 \partial_\nu u_0|_{\partial\Omega} = g.$$

(e.g., Kang/Seo/Sheen 1997, Ikehata 1998)

## Monotonicity based imaging

- ▶ Monotonicity:

$$\tau \leq \sigma \implies \Lambda(\tau) \geq \Lambda(\sigma)$$

- ▶ Idea: Simulate  $\Lambda(\tau)$  for test cond.  $\tau$  and compare with  $\Lambda(\sigma)$ .  
(*Tamburrino/Rubinacci 02, Lionheart, Soleimani, Ventre, ...*)
- ▶ Inclusion detection: For  $\sigma = 1 + \chi_A$  with unknown anomaly  $A$ , use  $\tau = 1 + \chi_B$ , with small ball  $B$ .

$$B \subseteq A \implies \tau \leq \sigma \implies \Lambda(\tau) \geq \Lambda(\sigma)$$

- ▶ Algorithm: Mark all balls  $B$  with  $\Lambda(1 + \chi_B) \geq \Lambda(\sigma)$
- ▶ Result: upper bound of anomaly  $A$ .

*Only an upper bound? Converse monotonicity relation?*



## Monotonicity method

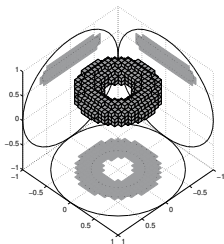
**Theorem** (H./Ullrich, 2013)

$D \setminus \bar{A}$  connected.  $\sigma = 1 + \chi_A$ .

$$B \subseteq A \iff \Lambda(1 + \chi_B) \geq \Lambda(\sigma).$$

For faster implementation:

$$B \subseteq A \iff \Lambda(1) + \frac{1}{2}\Lambda'(1)\chi_B \geq \Lambda(\sigma).$$




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Inclusion can be reconstructed by linearized monotonicity tests.

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- ~> Fast, rigorous, allows globally convergent implementation
  - ▶ Ideas of proof evolved from the similar **Factorization Method**  
 (For EIT: Arridge, Betcke, Brühl, Chaulet, Choi, Hakula, Hanke, H., Holder, Hyvönen, Kirsch, Lechleiter, Nachman, Päivärinta, Pursiainen, Schappel, Schmitt, Seo, Teirilä, ...)

## Calderón problem

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Deterministic Calderón Problem: Can we recover  $\sigma$  from NtD

$$\Lambda(\sigma) : L^2_{\diamond}(\partial D) \rightarrow L^2_{\diamond}(\partial D), \quad g \mapsto u|_{\partial D},$$

where  $u$  solves  $\nabla \cdot (\sigma \nabla u) = 0$  with  $\sigma \partial_{\nu} u|_{\partial D} = g$ ?

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- ▶ Stochastic Calderón problem:

*Can we recover  $\mathbb{E}(\sigma)$  from  $\mathbb{E}(\Lambda(\sigma))$ ?*

- ▶ Stochastic inclusion detection in hom. background ( $\sigma_0 = 1$ ):

*Can we recover  $\text{supp}(\mathbb{E}(\sigma) - 1)$  from  $\mathbb{E}(\Lambda(\sigma))$ ?*

- ▶ (Possible) Application: Biomedical anomaly detection from temporally averaged measurements.

## Detecting stochastic inclusions

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**Theorem** (*Barth/H./Hyvönen/Mustonen, submitted*)

Consider a domain with with a stochastic inclusion  $A$ ,

$$\sigma = \begin{cases} 1 & \text{in } D \setminus A, \\ \sigma_A(x, \omega) & \text{in } A, \end{cases}$$

- ▶  $\sigma_A : \Omega \rightarrow L_+^\infty(A)$ ,  $\Omega$  probability space,
- ▶  $\sigma_A, \sigma_A^{-1} \in L^1(\Omega, L_+^\infty(A))$

If

$$\mathbb{E}(\sigma_A) > 1 \quad \text{and} \quad \mathbb{E}(\sigma_A^{-1})^{-1} > 1,$$

then, both, the Factorization Method and the Monotonicity Method applied to  $\mathbb{E}(\sigma)$  recover the inclusion  $A$ .

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## Monotonicity for stochastic inclusions

Main idea of the proof: Monotonicity for stochastic inclusions:

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For deterministic  $\sigma_0$  and stochastic  $\sigma$ :

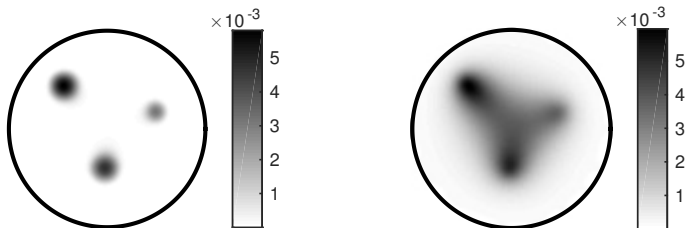
$$\begin{aligned} \int_D (\mathbb{E}(\sigma) - \sigma_0) |\nabla u_0|^2 dx &\geq \int_{\partial D} g(\Lambda(\sigma_0) - \mathbb{E}(\Lambda(\sigma))) g ds \\ &\geq \int_D \sigma_0^2 (\sigma_0^{-1} - \mathbb{E}(\sigma^{-1})) |\nabla u_0|^2 dx. \end{aligned}$$

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In particular,

$$\sigma_0 \leq \mathbb{E}(\sigma) \text{ and } \sigma_0 \leq \mathbb{E}(\sigma^{-1})^{-1} \implies \Lambda(\sigma_0) \geq \mathbb{E}(\Lambda(\sigma))$$

## Example



- ▶ Background conductivity  $\sigma_0 = 1$
- ▶ Inclusions conductivity uniformly distributed in  $[0.5, 3.5]$

$$\mathbb{E}(\sigma_A) \geq \mathbb{E}(\sigma_A^{-1})^{-1} \approx 1.54 > 1 = \sigma_0$$

- ▶ Images show result of Factorization Method applied to  $\mathbb{E}(\sigma)$   
 (Left Image: no noise, Right Image: 0.1% noise)

## Conclusions

In EIT, stochastic inclusions in a deterministic background

- ▶ can be detected by deterministic Factorization or Monotonicity Method applied to the measurement's expectation value,
- ▶ if, both,  $\mathbb{E}(\sigma_A)$  and  $\mathbb{E}(\sigma_A^{-1})^{-1}$  are larger than bg conductivity (or both are smaller than background conductivity)

Roughly speaking,

- ▶ stochastic conductivity uncertainty in  $\sigma$  is analogous to deterministic uncertainty in  $[\mathbb{E}(\sigma^{-1})^{-1}, \mathbb{E}(\sigma)]$

Outlook:

- ▶ Stochastic inclusions in stochastic backgrounds may be treatable by resolution guarantees  
(Deterministic case: **H.**, *Ullrich, IEEE TMI 2015*)