



# Inverse parameter identification problems

Bastian von Harrach

[harrach@math.uni-stuttgart.de](mailto:harrach@math.uni-stuttgart.de)

Chair of Optimization and Inverse Problems, University of Stuttgart, Germany

ICP - Institute for Computational Physics,  
June 27, 2013.



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# Contents

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- ▶ Parameter identification problems  
in diffuse optical tomography (DOT)
- ▶ Linearized reconstruction algorithms  
in electrical impedance tomography (EIT)



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# Parameter identification problems

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in diffuse optical tomography (DOT)



# Diffuse optical tomography

Diffuse optical tomography (DOT):

- ▶ Transilluminate biological tissue with visible/near-infrared light
- ▶ **Goal:** Reconstruct spatial image of interior physical properties.

Relevant quantities (in diffusive regime):

- ▶ Scattering
- ▶ Absorption
- ▶ **Applications:**
  - ▶ Breast cancer detection
  - ▶ Bedside-imaging of neonatal brain function

# Diffuse optical tomography



Figure 1 from Gibson, Hebden and Arridge (Phys. Med. Biol. 50, R1–R43, 2005)  
Imaging Diagnostic System Inc.'s computed tomography laser breast imaging system.  
See [www.imds.com](http://www.imds.com) for more details.

# Mathematical Model

- ▶ General Forward Model:

Photon transport models (Boltzmann transport equation)

cf., e.g., Bal, Inverse Problems 25, 053001 (48pp), 2009.

- ▶ For highly scattering media:

- ▶ DC diffusion approximation for photon density  $u$ :

$$-\nabla \cdot (a \nabla u) + cu = 0 \quad \text{in } B \subset \mathbb{R}^n,$$

$u : B \rightarrow \mathbb{R}$ : photon density

$a : B \rightarrow \mathbb{R}$ : diffusion/scattering coefficient

$c : B \rightarrow \mathbb{R}$ : absorption coefficient

- ▶ Boundary measurements (idealized):

Neumann and Dirichlet data  $u|_S$ ,  $a\partial_\nu u|_S$  on  $S \subseteq \partial B$ .

Remaining boundary assumed to be insulated,  $a\partial_\nu u|_{\partial B \setminus S} = 0$ .

# Forward & inverse problem

DC diffuse optical tomography:

$$-\nabla \cdot (a \nabla u) + cu = 0 \quad \text{in } B \subset \mathbb{R}^n, n \geq 2,$$

$B$  bounded with smooth bndry,  $S \subseteq \partial B$  open part,  $a, c \in L_+^\infty(B)$ .

- ▶  $\forall g \in L^2(S) \exists! \text{ sol. } u \in H^1(B) : a\partial_\nu u|_{\partial B} = \begin{cases} g & \text{on } S, \\ 0 & \text{on } B \setminus \bar{S}. \end{cases}$
- ▶ (Local) Neumann-to-Dirichlet map

$$\Lambda_{a,c} : g \mapsto u|_S, \quad L^2(S) \rightarrow L^2(S)$$

is linear, compact and self-adjoint.

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Inverse Problem: Can we reconstruct  $a$  and  $c$  from  $\Lambda_{a,c}$ ?

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## Non-uniqueness

DC diffuse optical tomography:

$$-\nabla \cdot (a \nabla u) + cu = 0$$

Arridge/Lionheart (1998 Opt. Lett. 23 882–4):

- ▶  $v := \sqrt{a}u$  solves

$$-\Delta v + \eta v = 0, \quad \text{with} \quad \eta = \frac{\Delta \sqrt{a}}{\sqrt{a}} + \frac{c}{a}.$$

- ▶  $a = 1$  around  $S \rightsquigarrow (u|_S, a\partial_\nu u|_S) = (v|_S, \partial_\nu v|_S).$
- rightsquigarrow  $\Lambda_{a,c}$  only depends on **effective absorption**  $\eta = \eta(a, c)$ .

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Absorption and scattering effects cannot be distinguished.

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(Note: Argument requires smooth scattering coefficient  $a$ ).

## Experimental results

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Theory: Absorption and scattering effects cannot be distinguished.

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Practice:

Successful separate reconstructions of absorption and scattering  
(from phantom experiment using dc diffusion model!)

Pei et al. (2001), Jiang et al. (2002), Schmitz et al. (2002), Xu et al. (2002)

~~> Practice contradicts theory!

Pei et al. (2001):

*"As a matter of established methodological principle (...) empirical facts have the right-of-way; if a theoretical derivation yields a conclusion that is at odds with experimental results, the reconciliatory burden falls on the theorist, not on the experimentalist."*

## New uniqueness result

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**Theorem** (H., Inverse Problems 2009)

- ▶  $a_1, a_2 \in L^\infty_+(B)$  piecewise constant
- ▶  $c_1, c_2 \in L^\infty_+(B)$  piecewise analytic

If  $\Lambda_{a_1, c_1} = \Lambda_{a_2, c_2}$  then  $a_1 = a_2$  and  $c_1 = c_2$ .

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- ▶ Piecewise constantness seems fulfilled for phantom experiments.
- ↝ Result reconciles theory with practice.
- ▶ Measurements contain more than just the effective absorption!

**Next slides:** Idea of the proof using monotony and loc. potentials.

# Monotony result

## Lemma

Let  $a_1, a_2, c_1, c_2 \in L_+^\infty(B)$ . Then for all  $g \in L^2(S)$ ,

$$\begin{aligned} & \int_B ((a_2 - a_1)|\nabla u_1|^2 + (c_2 - c_1)|u_1|^2) \, dx \\ & \geq \langle (\Lambda_{a_1, c_1} - \Lambda_{a_2, c_2})g, g \rangle \\ & \geq \int_B ((a_2 - a_1)|\nabla u_2|^2 + (c_2 - c_1)|u_2|^2) \, dx, \end{aligned}$$

$u_1, u_2 \in H^1(B)$ : solutions for  $(a_1, c_1)$ , resp.,  $(a_2, c_2)$ .

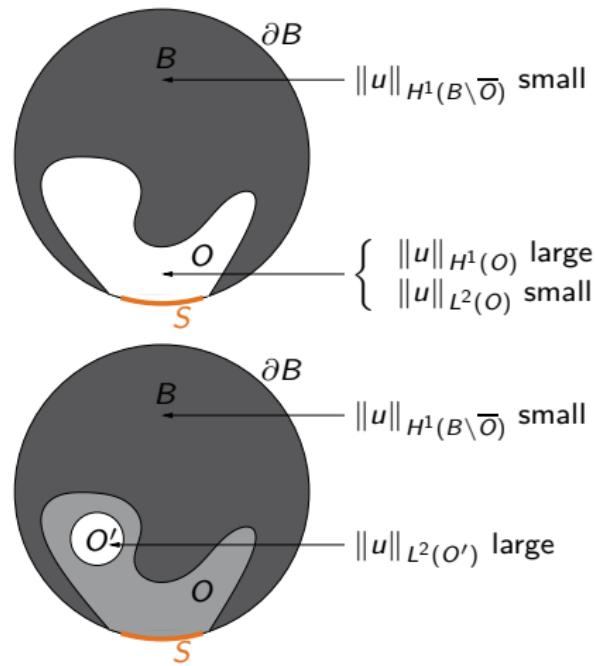
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Can we control  $|u_j|^2$  and  $|\nabla u_j|^2$ ?

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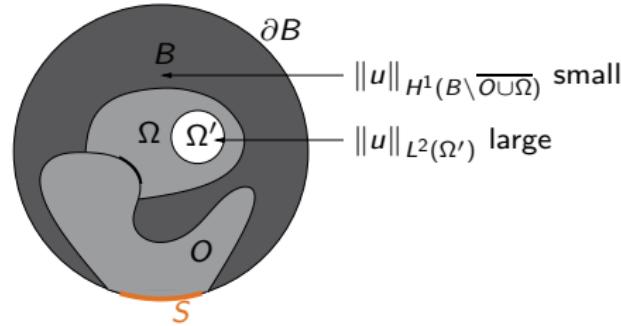
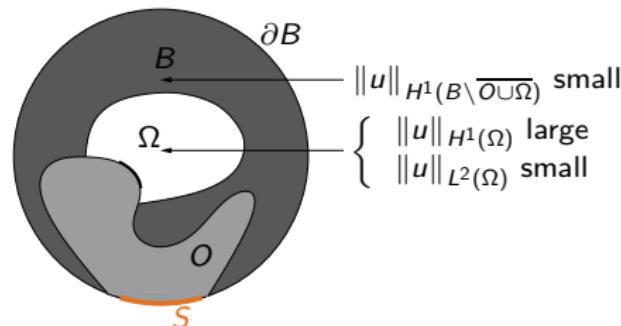
## Localized potentials

**Lemma** There exist solutions  $u$  with



## Localized potentials

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# Proof of uniqueness

## Monotony

$$\begin{aligned} & \int_B ((a_2 - a_1)|\nabla u_1|^2 + (c_2 - c_1)|u_1|^2) \, dx \\ & \geq \langle (\Lambda_{a_1, c_1} - \Lambda_{a_2, c_2})g, g \rangle \\ & \geq \int_B ((a_2 - a_1)|\nabla u_2|^2 + (c_2 - c_1)|u_2|^2) \, dx, \end{aligned}$$

## Proof of the uniqueness result (*very sketchy ...*)

Start with region next to  $S$

- ▶ Use loc. pot. with  $|\nabla u|^2 \rightarrow \infty$  in that region  $\rightsquigarrow a_1 = a_2$
- ▶ Then use loc. pot. with  $|u|^2 \rightarrow \infty$  in that region  $\rightsquigarrow c_1 = c_2$
- ▶ Repeat over all regions.

## Uniqueness or not?

- ▶ Arridge/Lionheart (1998): Non-uniqueness for general smooth  $(a, c)$ .
- ▶ H. (2009): Uniqueness for piecew. constant  $a$ , piecew. analytic  $c$ .

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What information about  $(a, c)$  does  $\Lambda_{a,c}$  really contain?

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Formally(!),  $\Lambda_{a,c}$  can only determine  $\eta = \frac{\Delta\sqrt{a}}{\sqrt{a}} + \frac{c}{a}$ .

Jumps in  $a$  or  $\nabla a$   $\rightsquigarrow$  distributional singularities in  $\Delta\sqrt{a}$ .

**Bold guess:** Maybe  $\Lambda_{a,c}$  determines

- ▶  $\eta$  where  $a$  and  $c$  are smooth,
- ▶ jumps in  $a$  and  $\nabla a$ .

(However, note that  $\Delta\sqrt{a}/\sqrt{a}$  is not well-defined for non-smooth  $a \dots$ )

# Exact characterization

**Theorem** ( H., Inverse Probl. Imaging 2012)

Let  $a_1, a_2, c_1, c_2 \in L_+^\infty(B)$  piecewise analytic on joint partition

$$B = O_1 \cup \dots \cup O_J \cup \Gamma, \quad \partial O_1 \cup \dots \cup \partial O_J = \partial B \cup \Gamma.$$

Then,  $\Lambda_{a_1, c_1} = \Lambda_{a_2, c_2}$  if and only if

$$(a) \quad a_1|_S = a_2|_S, \quad \text{and} \quad \partial_\nu a_1|_S = \partial_\nu a_2|_S \quad \text{on } S,$$

$$(b) \quad \frac{\partial_\nu a_1}{a_1}|_{\partial B \setminus \overline{S}} = \frac{\partial_\nu a_2}{a_2}|_{\partial B \setminus \overline{S}} \quad \text{on } \partial B \setminus \overline{S},$$

$$(c) \quad \eta_1 := \frac{\Delta \sqrt{a_1}}{\sqrt{a_1}} + \frac{c_1}{a_1} = \frac{\Delta \sqrt{a_2}}{\sqrt{a_2}} + \frac{c_2}{a_2} =: \eta_2 \quad \text{on } B \setminus \Gamma,$$

$$(d) \quad \frac{a_1^+|_\Gamma}{a_1^-|_\Gamma} = \frac{a_2^+|_\Gamma}{a_2^-|_\Gamma}, \quad \text{and} \quad \frac{[\partial_\nu a_2]_\Gamma}{a_2^-|_\Gamma} = \frac{[\partial_\nu a_1]_\Gamma}{a_1^-|_\Gamma} \quad \text{on } \Gamma.$$



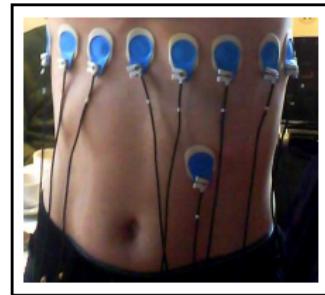
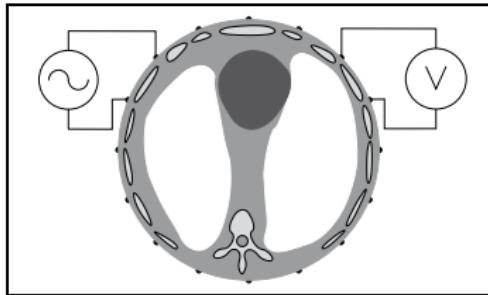
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# Linearized reconstruction algorithms

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in electrical impedance tomography (EIT)

# EIT



Electrical impedance tomography (EIT):

- ▶ Apply currents  $\sigma \partial_\nu u|_{\partial B}$  (Neumann boundary data)
  - ~~> Electric potential  $u$  solves

$$\nabla \cdot (\sigma \nabla u) = 0 \quad \text{in } B$$

- ▶ Measure voltages  $u|_{\partial B}$  (Dirichlet boundary data)

Current-Voltage-Measurements ~~> Neumann-to-Dirichlet map  $\Lambda(\sigma)$



## Inverse problem

Non-linear forward operator of EIT

$$\Lambda : \sigma \mapsto \Lambda(\sigma), \quad L_+^\infty(B) \rightarrow \mathcal{L}(L_\diamond^2(\partial B))$$

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Inverse problem of EIT:       $\Lambda(\sigma) \mapsto \sigma?$

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Localized potentials  $\rightsquigarrow$  Uniqueness for piecew. analytic conductivities  
already known: Druskin (1982+85), Kohn/Vogelius (1984+85)

# Linearization

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Generic approach: Linearization

$$\Lambda(\sigma) - \Lambda(\sigma_0) \approx \Lambda'(\sigma_0)(\sigma - \sigma_0)$$

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$\sigma_0$ : known reference conductivity / initial guess / ...

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$\Lambda'(\sigma_0)$ : Fréchet-Derivative / sensitivity matrix.

$$\Lambda'(\sigma_0) : L_+^\infty(B) \rightarrow \mathcal{L}(L_\diamond^2(\partial B)).$$

~> Solve linearized equation for difference  $\sigma - \sigma_0$ .

Often:  $\text{supp}(\sigma - \sigma_0) \subset\subset B$  compact. ("shape" / "inclusion")



# Linearization

## Linear reconstruction method

e.g. NOSER (Cheney et al., 1990), GREIT (Adler et al., 2009)

Solve  $\Lambda'(\sigma_0)\kappa \approx \Lambda(\sigma) - \Lambda(\sigma_0)$ , then  $\kappa \approx \sigma - \sigma_0$ .

- ▶ Multiple possibilities to measure residual norm and to regularize.
- ▶ No rigorous theory for single linearization step.
- ▶ Almost no theory for Newton iteration:
  - ▶ Dobson (1992): (Local) convergence for regularized EIT equation.
  - ▶ Lechleiter/Rieder(2008): (Local) convergence for discretized setting.
  - ▶ No (local) convergence theory for non-discretized case!



# Linearization

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## Linear reconstruction method

e.g. NOSER (Cheney et al., 1990), GREIT (Adler et al., 2009)

Solve  $\Lambda'(\sigma_0)\kappa \approx \Lambda(\sigma) - \Lambda(\sigma_0)$ , then  $\kappa \approx \sigma - \sigma_0$ .

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- ▶ **Seemingly**, no rigorous results possible for single lineariz. step.
- ▶ **Seemingly**, only justifiable for small  $\sigma - \sigma_0$  (local results).

**Here:** Rigorous and global(!) result about the linearization error.

# Exact Linearization

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**Theorem** (H./Seo, SIAM J. Math. Anal. 2010)

Let  $\kappa, \sigma, \sigma_0$  piecewise analytic and  $\Lambda'(\sigma_0)\kappa = \Lambda(\sigma) - \Lambda(\sigma_0)$ . Then

$$\text{supp}_{\partial B}\kappa = \text{supp}_{\partial B}(\sigma - \sigma_0)$$

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$\text{supp}_{\partial B}$ : outer support (= support, if support is compact and has conn. complement)

- ▶ Exact solution of lin. equation yields correct (outer) shape.
- ▶ No assumptions on  $\sigma - \sigma_0$ !
- ~~ Linearization error does not lead to shape errors.

**Proof:** Combination of monotony and localized potentials.

# Proof

- ▶ Exact linearization:  $\Lambda'(\sigma_0)\kappa = \Lambda(\sigma) - \Lambda(\sigma_0)$
- ▶ Monotony: For all "reference solutions"  $u_0$ :

$$\begin{aligned}
 & \int_B (\sigma - \sigma_0) |\nabla u_0|^2 \, dx \\
 & \geq \underbrace{\langle g, (\Lambda(\sigma) - \Lambda(\sigma_0)) g \rangle}_{= \int_B \kappa |\nabla u_0|^2 \, dx} \geq \int_B \frac{\sigma_0}{\sigma} (\sigma - \sigma_0) |\nabla u_0|^2 \, dx.
 \end{aligned}$$

- ▶ Use **localized potentials** to control  $|\nabla u_0|^2$
- ⇝  $\text{supp}_{\partial\Omega}\kappa = \text{supp}_{\partial\Omega}(\sigma - \sigma_0)$

## Interpretation

$\sigma_0$ : reference conductivity

$\sigma$  : true conductivity

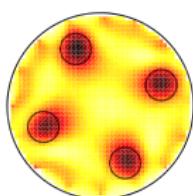
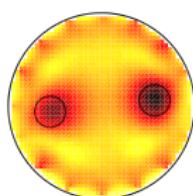
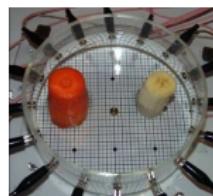
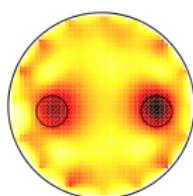
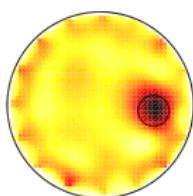
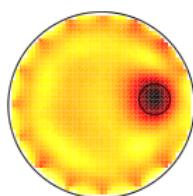
- ▶ Current paths depend on unknown conductivity  $\sigma$  (Non-linearity of EIT)
- ▶ Linearizing EIT around ref. conductivity  $\sigma_0$  corresponds to assuming that currents take the same paths as in a ref. body.
- ▶ Paths may differ considerably when  $\sigma - \sigma_0$  is large.
- ▶ However, taking the (wrong) reference paths for reconstruction still yields the correct shape information!

**Practical issues:** Theorem requires exact sol. of linearized equation

- ▶ Does an approximate solution of the linearized equation show approximately correct shapes?

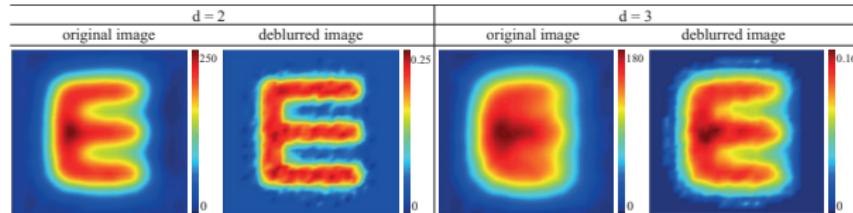
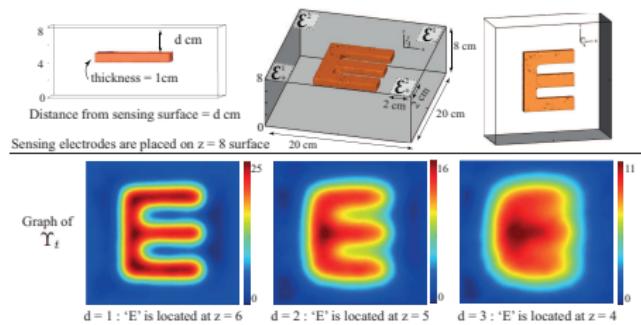
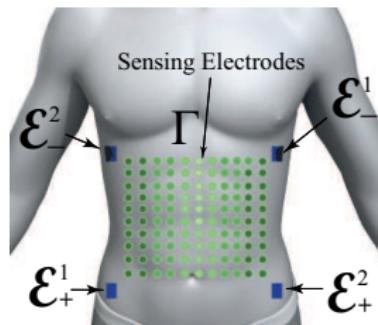
# Experimental result (frequency difference data)

H./Seo/Woo (*IEEE Trans. Med. Imaging 2010*):  
Heuristic combination of linearization and localized potentials for fdEIT.



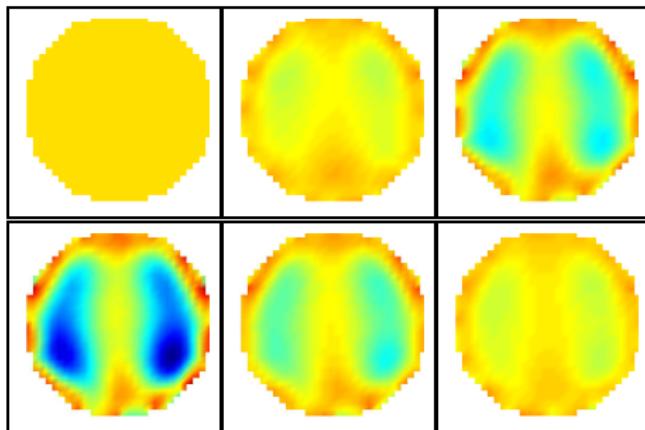
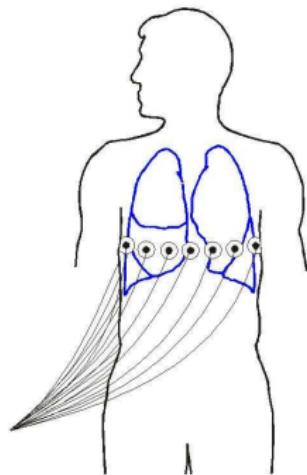
# Planar EIT

Ts/Lee/Seo/H./Kim (submitted): Partial inversion plus linearization



# Lung monitoring - real human data

*BMBF-project on regularizing EIT in the medical and geophysical sciences.*



# Conclusion

- ▶ Novel tomography techniques lead to mathematical parameter identification problems.
- ▶ Uniqueness questions may have non-trivial answers.  
In diffuse optical tomography:
  - ▶ Effective absorption plus jumps in diffusion coefficient (and its derivative) can be reconstructed simultaneously.
  - ~~> Uniqueness for piecewise constant coefficients, but not for general smooth coefficients
- ▶ Non-linearity is main challenge for stable/convergent algos.
  - ▶ Shape information is not affected by linearization errors.
  - ▶ Stable shape reconstruction is possible.
- ▶ Close interplay between uniqueness arguments and convergent reconstruction algorithms.