



Inverse coefficient problems and shape reconstruction

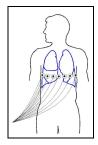
Bastian von Harrach harrach@math.uni-stuttgart.de

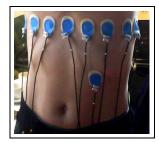
Chair of Optimization and Inverse Problems, University of Stuttgart, Germany

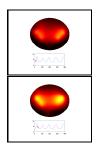
Applied Inverse Problem Conference Korea Advanced Institute for Sciences and Technology, Daejeon, Korea, July 1-5, 2013.



Electrical impedance tomography (EIT)







- Apply electric currents on subject's boundary
- Measure necessary voltages
- → Reconstruct conductivity inside subject.

Images from BMBF-project on EIT

(Hanke, Kirsch, Kress, Hahn, Weller, Schilcher, 2007-2010)



Mathematical Model

Electrical potential u(x) solves $abla \cdot (\sigma(x) abla u(x)) = 0 \quad x \in \Omega$

- $\Omega \subset \mathbb{R}^n$: imaged body, $n \geq 2$
 - $\sigma(x)$: conductivity
 - u(x): electrical potential

Idealistic model for boundary measurements (continuum model):

 $\sigma \partial_{\nu} u(x)|_{\partial\Omega}$: applied electric current $u(x)|_{\partial\Omega}$: measured boundary voltage (potential)



Calderón problem

Can we recover $\sigma \in L^\infty_+(\Omega)$ in

$$abla \cdot (\sigma \nabla u) = 0, \quad x \in \Omega$$
 (1)

from all possible Dirichlet and Neumann boundary values

 $\{(u|_{\partial\Omega}, \sigma\partial_{\nu}u|_{\partial\Omega}) : u \text{ solves } (1)\}?$

Equivalent: Recover σ from Neumann-to-Dirichlet-Operator

 $\Lambda(\sigma): \ L^2_{\diamond}(\partial\Omega) \to L^2_{\diamond}(\partial\Omega), \quad g \mapsto u|_{\partial\Omega},$

where *u* solves (1) with $\sigma \partial_{\nu} u |_{\partial \Omega} = g$.



Partial/local data

Measurements on open part of boundary $\Sigma \subset \partial \Omega$: ($\partial \Omega \setminus \Sigma$ is kept insulated.)

Recover σ from

$$\Lambda(\sigma): \ L^2_\diamond(\Sigma) \to L^2_\diamond(\Sigma), \quad g \mapsto u|_{\Sigma},$$

where *u* solves $\nabla \cdot (\sigma \nabla u) = 0$ with

$$\sigma \partial_{\nu} u|_{\Sigma} = \begin{cases} g & \text{on } \Sigma, \\ 0 & \text{else.} \end{cases}$$





Challenges

Challenges in inverse coefficient problems such as EIT:

- Uniqueness
 - Is σ uniquely determined from the NtD $\Lambda(\sigma)$?
- Non-linearity and ill-posedness
 - Reconstruction algorithms to determine σ from $\Lambda(\sigma)$?
 - Local/global convergence results?
- Realistic data
 - What can we recover from real measurements? (Finite number of electrodes, realistic electrode models, ...)
 - Measurement and modelling errors? Resolution?

In this talk: A simple strategy (monotonicity + localized potentials) to attack these challenges.





Uniqueness

University of Stuttgart Germany

Uniqueness results

- Measurements on complete boundary (full data): Calderón (1980), Druskin (1982+85), Kohn/Vogelius (1984+85), Sylvester/Uhlmann (1987), Nachman (1996), Astala/Päivärinta (2006)
- Measurements on part of the boundary (local data): Bukhgeim/Uhlmann (2002), Knudsen (2006), Isakov (2007), Kenig/Sjöstrand/Uhlmann (2007), H. (2008), Imanuvilov/Uhlmann/Yamamoto (2009+10), Kenig/Salo (2012+13)
- L^{∞} coefficients are uniquely determined from full data in 2D.
- ▶ In all cases, piecew.-anal. coefficients are uniquely determined.
- ► Sophisticated research on uniqueness for $\approx C^2$ -coefficients (based on CGO-solutions for Schrödinger eq. $-\Delta u + qu = 0$, $q = \frac{\Delta\sqrt{\sigma}}{\sqrt{\sigma}}$).



Monotonicity

For two conductivities $\sigma_0, \sigma_1 \in L^{\infty}(\Omega)$:

$$\sigma_0 \leq \sigma_1 \implies \Lambda(\sigma_0) \geq \Lambda(\sigma_1)$$

This follows from

$$\int_{\Omega} (\sigma_1 - \sigma_0) |\nabla u_0|^2 \geq \int_{\Sigma} g \left(\Lambda(\sigma_0) - \Lambda(\sigma_1) \right) g \geq \int_{\Omega} \frac{\sigma_0}{\sigma_1} (\sigma_1 - \sigma_0) |\nabla u_0|^2$$

for all solutions u_0 of

$$abla \cdot (\sigma_0 \nabla u_0) = 0, \quad \sigma_0 \partial_{\nu} u_0|_{\Sigma} = \left\{ egin{array}{cc} g & \mbox{on } \Sigma, \ 0 & \mbox{else.} \end{array}
ight.$$

(e.g., Kang/Seo/Sheen 1997, Ikehata 1998)

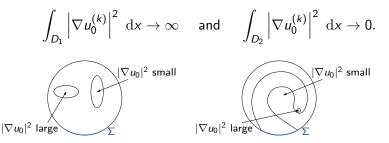
Can we prove uniqueness by controlling $|\nabla u_0|^2$?



Localized potentials

Theorem (H., 2008) Let σ_0 fulfill unique continuation principle (UCP),

 $\overline{D_1} \cap \overline{D_2} = \emptyset$, and $\Omega \setminus (\overline{D}_1 \cup \overline{D}_2)$ be connected with Σ . Then there exist solutions $u_0^{(k)}$, $k \in \mathbb{N}$ with



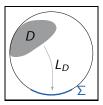


Proof 1/3

Virtual measurements:

$$L_D: H^1_{\diamond}(D)' \to L^2_{\diamond}(\Sigma), \quad f \mapsto u|_{\Sigma}, \text{ with}$$

$$\int_{\Omega} \sigma \nabla u \cdot \nabla v \, \mathrm{d}x = \langle f, v |_D \rangle \quad \forall v \in H^1_{\diamond}(D).$$



By (UCP): If $\overline{D_1} \cap \overline{D_2} = \emptyset$ and $\Omega \setminus (\overline{D}_1 \cup \overline{D}_2)$ is connected with Σ , then $\mathcal{R}(L_{D_1}) \cap \mathcal{R}(L_{D_2}) = 0$.

Sources on different domains yield different virtual measurements.

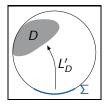


Proof 2/3

Dual operator:

$$\mathcal{L}'_D: \ \mathcal{L}^2_\diamond(\Sigma) \to \mathcal{H}^1_\diamond(D), \quad g \mapsto u|_D,, \text{ with}$$

 $\nabla \cdot (\sigma \nabla u) = 0, \quad \sigma \partial_{\nu} u|_{\Sigma} = \begin{cases} g & \text{on } \Sigma, \\ 0 & \text{else.} \end{cases}$



Evaluating solutions on D is dual operation to virtual measurements.



Proof 3/3

Functional analysis: X, Y_1, Y_2 reflexive Banach spaces, $L_1 \in \mathcal{L}(Y_1, X), L_2 \in \mathcal{L}(Y_1, X)$. $\mathcal{R}(L_1) \subseteq \mathcal{R}(L_2) \iff \|L'_1 x\| \lesssim \|L'_2 x\| \ \forall x \in X'$. Here: $\mathcal{R}(L_{D_1}) \not\subseteq \mathcal{R}(L_{D_2}) \implies \|u_0|_{D_1}\|_{H^1_0} \not\lesssim \|u_0|_{D_2}\|_{H^1_0}$.

If two sources do not generate the same data, then the respective evaluations are not bounded by each other.

Note: $H^1_{\diamond}(D)'$ -source \longleftrightarrow $H^1_{\diamond}(D)$ -evaluation.



Consequences

- ▶ Back to Calderón: Let $\Lambda(\sigma_0) = \Lambda(\sigma_1)$, σ_0 fulfills (UCP).
- By monotonicity,

$$\int_{\Omega} (\sigma_1 - \sigma_0) |\nabla u_0|^2 \, \mathrm{d} x \ge 0 \ge \int_{\Omega} \frac{\sigma_0}{\sigma_1} (\sigma_1 - \sigma_0) |\nabla u_0|^2 \, \mathrm{d} x \quad \forall u_0$$

- ► Assume: ∃ neighbourhood *U* of Σ where $\sigma_1 \ge \sigma_0$ but $\sigma_1 \ne \sigma_0$
- \rightsquigarrow Potential with localized energy in U contradicts monotonicity

Higher conductivity reachable by the bndry cannot be balanced out.

Corollary (Druskin 1982+85, Kohn/Vogelius, 1984+85) Calderón problem is uniquely solvable for piecw.-anal. conductivities.



(1)

Two coefficients

Can we recover two coefficients $a, c \in L^\infty_+(\Omega)$ in

$$-
abla \cdot (a
abla u) + c u = 0$$
 in Ω

from the NtD (with partial data)

$$\Lambda(a,c): \ L^2(\Sigma) \to L^2(\Sigma), \quad g \mapsto u|_{\Sigma},$$

where u solves (1) with

$$\sigma \partial_{\nu} u|_{\Sigma} = \begin{cases} g & \text{on } \Sigma, \\ 0 & \text{else.} \end{cases}$$

Application: Diffuse optical tomography (DOT).



Monotonicity

$$\begin{split} &\int_{\Omega} \left((a_2 - a_1) |\nabla u_1|^2 + (c_2 - c_1) |u_1|^2 \right) \, \mathrm{d}x \\ &\geq \int_{\Sigma} g \left(\Lambda(a_1, c_1) - \Lambda(a_2, c_2) \right) g \, \mathrm{d}s \\ &\geq \int_{\Omega} \left((a_2 - a_1) |\nabla u_2|^2 + (c_2 - c_1) |u_2|^2 \right) \, \mathrm{d}x, \end{split}$$

Method of localized potentials:

- Again, sources on different regions produce different data.
- $(H^1)'$ -sources produce different data than L^2 -sources

 $\implies \|u\|_{H^1(D)} \lesssim \|u\|_{L^2(D)}.$

We can control $|\nabla u_1|^2$ and $|u_1|^2$ separately.



Uniqueness

Theorem (H., 2009) Let

- ▶ $a_1, a_2 \in L^\infty_+(\Omega)$ piecewise constant,
- $c_1, c_2 \in L^{\infty}_+(\Omega)$ piecewise analytic.

Then

$$\Lambda(a_1,c_1)=\Lambda(a_2,c_2)\quad\Longleftrightarrow\quad a_1=a_2,\quad c_1=c_2.$$

Note that $v := \sqrt{a}u$ transforms $-\nabla \cdot (a\nabla u) + cu = 0$ into

$$-\Delta v + \eta v = 0, \quad \eta := rac{\Delta \sqrt{a}}{\sqrt{a}} + rac{c}{a}$$

(when the coefficients are smooth).



Uniqueness

Theorem (H., 2012) Let $a_1, a_2, c_1, c_2 \in L^{\infty}_{+}(\Omega)$ be piecew. analytic. Then $\Lambda(a_1, c_1) = \Lambda(a_2, c_2)$ if and only if (a) $a_1|_{\Sigma} = a_2|_{\Sigma}, \quad \partial_{\nu}a_1|_{\Sigma} = \partial_{\nu}a_2|_{\Sigma}$ on Σ. $\frac{\partial_{\nu}a_{1}}{a_{1}}|_{\partial B\setminus\overline{S}} = \frac{\partial_{\nu}a_{2}}{a_{2}}|_{\partial B\setminus\overline{S}}$ (b) on $\partial \Omega \setminus \Sigma$, (c) in smooth regions, $\eta_1 = \eta_2$ (d) $\frac{a_1^+|_{\Gamma}}{a_2^-|_{\Gamma}} = \frac{a_2^+|_{\Gamma}}{a_2^-|_{\Gamma}}, \quad \frac{[\partial_{\nu}a_2]_{\Gamma}}{a_2^-|_{\Gamma}} = \frac{[\partial_{\nu}a_1]_{\Gamma}}{a_2^-|_{\Gamma}}$ on inner boundaries Γ . NtD $\Lambda_{(a,c)}$ determines $\eta = \frac{\Delta\sqrt{a}}{\sqrt{a}} + \frac{c}{a}$ and the jumps of a and ∇a .





Non-linearity



Non-linearity

Back to the non-linear forward operator of EIT

$$\Lambda: \ \sigma \mapsto \Lambda(\sigma), \quad L^{\infty}_{+}(\Omega) \to \mathcal{L}(L^{2}_{\diamond}(\Sigma))$$

Generic approach for inverting Λ : Linearization

$$\Lambda(\sigma) - \Lambda(\sigma_0) \approx \Lambda'(\sigma_0)(\sigma - \sigma_0)$$

 $\sigma_0:$ known reference conductivity / initial guess / \ldots

 $\Lambda'(\sigma_0)$: Fréchet-Derivative / sensitivity matrix.

$$\Lambda'(\sigma_0): L^{\infty}_+(\Omega) \to \mathcal{L}(L^2_{\diamond}(\Sigma)).$$

 \sim → Solve linearized equation for difference $\sigma - \sigma_0$. Often: supp($\sigma - \sigma_0$) ⊂ Ω ("shape" / "inclusion") B. Harrach: Inverse coefficient problems and shape reconstruction



Linearization

Linear reconstruction method

e.g. NOSER (Cheney et al., 1990), GREIT (Adler et al., 2009) Solve $\Lambda'(\sigma_0)\kappa \approx \Lambda(\sigma) - \Lambda(\sigma_0)$, then $\kappa \approx \sigma - \sigma_0$.

- Multiple possibilities to measure residual norm and to regularize.
- No rigorous theory for single linearization step.
- Almost no theory for Newton iteration:
 - ▶ Dobson (1992): (Local) convergence for regularized EIT equation.
 - Lechleiter/Rieder(2008): (Local) convergence for discretized setting.
 - No (local) convergence theory for non-discretized case!
 Non-linearity condition (Scherzer / tangential cone cond.) still open problem
- ► D-bar method: convergent 2D-implementation for σ ∈ C² and full bndry data (Knudsen, Lassas, Mueller, Siltanen 2008)



Linearization

Linear reconstruction method

e.g. NOSER (Cheney et al., 1990), GREIT (Adler et al., 2009) Solve $\Lambda'(\sigma_0)\kappa \approx \Lambda(\sigma) - \Lambda(\sigma_0)$, then $\kappa \approx \sigma - \sigma_0$.

- Seemingly, no rigorous results possible for single lineariz. step.
- Seemingly, only justifiable for small $\sigma \sigma_0$ (local results).

Here: Rigorous and global(!) result about the linearization error.



Linearization and shape reconstruction

Theorem (H./Seo 2010)

Let κ , σ , σ_0 piecewise analytic and $\Lambda'(\sigma_0)\kappa = \Lambda(\sigma) - \Lambda(\sigma_0)$. Then

$$\operatorname{supp}_{\Sigma} \kappa = \operatorname{supp}_{\Sigma} (\sigma - \sigma_0)$$

 $\operatorname{supp}_{\Sigma}$: outer support (= support, if support is compact and has conn. complement)

- Solution of lin. equation yields correct (outer) shape.
- No assumptions on $\sigma \sigma_0!$
- \rightsquigarrow Linearization error does not lead to shape errors.

Taking the (wrong) reference current paths for reconstruction still yields the correct shape information!



Proof

- Linearization: $\Lambda'(\sigma_0)\kappa = \Lambda(\sigma) \Lambda(\sigma_0)$
- ► Monotonicity: For all "reference solutions" *u*₀:

$$\int_{\Omega} (\sigma - \sigma_0) |\nabla u_0|^2 \, \mathrm{d}x$$

$$\geq \underbrace{\int_{\Sigma} g \left(\Lambda(\sigma_0) - \Lambda(\sigma) \right) g}_{= \int_{\Omega} \varphi \left(\Lambda'(\sigma_0) \kappa \right) g = \int_{\Omega} \kappa |\nabla u_0|^2 \, \mathrm{d}x.$$

• Use localized potentials to control $|\nabla u_0|^2$ $\Rightarrow \operatorname{supp}_{\Sigma} \kappa = \operatorname{supp}_{\Sigma} (\sigma - \sigma_0)$

In shape reconstruction problems we can avoid non-linearity.





Reconstruction from realistic data



Monotonicity based imaging

Monotonicity:

$$au \leq \sigma \implies \Lambda(au) \geq \Lambda(\sigma)$$

- Idea: Simulate Λ(τ) for test cond. τ and compare with Λ(σ). (Tamburrino/Rubinacci 02, Lionheart, Soleimani, Ventre, ...)
- Inclusion detection: For σ = 1 + χ_D with unknown D, use τ = 1 + χ_B, with small ball B.

$$B \subseteq D \implies \tau \leq \sigma \implies \Lambda(\tau) \geq \Lambda(\sigma)$$

- Algorithm: Mark all balls B with $\Lambda(1 + \chi_B) \ge \Lambda(\sigma)$
- Result: upper bound of D.

Only an upper bound? Converse monotonicity relation?

B. Harrach: Inverse coefficient problems and shape reconstruction



Converse monotonicity relation

Theorem (H./Ullrich, submitted) $\Omega \setminus \overline{D}$ connected. $\sigma = 1 + \chi_D$.

$$B \subseteq D \iff \Lambda(1 + \chi_B) \ge \Lambda(\sigma).$$

→ Monotonicity method detects exact shape.

For faster implementation:

$$B \subseteq D \iff \Lambda(1) + \frac{1}{2}\Lambda'(1)\chi_B \ge \Lambda(\sigma).$$

~> Linearized monotonicity method detects exact shape.

Proof: Monotonicity + localized potentials



General case

Theorem (H./Ullrich, submitted). Let $\sigma \in L^{\infty}_{+}(\Omega)$ be piecewise analytic. The intersection of all *hole-free* $C \subseteq \overline{\Omega}$ with

$$\exists \alpha > 1: \ \Lambda(1 + \alpha \chi_{\mathcal{C}}) \leq \Lambda(\sigma) \leq \Lambda(1 - \chi_{\mathcal{C}}/\alpha)$$

is identical to the *(outer)* support of $\sigma - 1$.

Result also holds with linearized condition

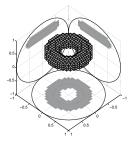
 $\exists \alpha > 1: \ \Lambda(1) + \alpha \Lambda'(1) \chi_{\mathcal{C}} \leq \Lambda(\sigma) \leq \Lambda(1) - \alpha \Lambda'(1) \chi_{\mathcal{C}}.$

► Result covers indefinite case, e.g., $\sigma = 1 + \chi_{D_1} - \frac{1}{2}\chi_{D_2}$



Monotonicity based reconstruction

- ▶ is intuitive, yet rigorous
- is stable (no infinity or range tests)
- works for pcw. anal. conductivities (no definiteness conditions)
- requires only the reference solution



University of Stuttgart

Approach is closely related to (and heavily inspired by)

- Factorization Method of Kirsch and Hanke (in EIT: Brühl, Hakula, H., Hyvönen, Lechleiter, Nachman, Päivärinta, Pursiainen, Schappel, Schmitt, Seo, Teirilä, Woo, ...)
- Ikehata's Enclosure Method and probing with Sylvester-Uhlmann-CGOs (Ide, Isozaki, Nakata, Siltanen, Wang, ...)
- Classic inclusion detection results (Friedmann, Isakov, ...)

University of Stuttgart Germany

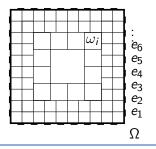
Realistic data & Uncertainties

- Finite number of electrodes, CEM, noisy data $\Lambda^{\delta}(\sigma)$
- ▶ Unknown background, e.g., $1 \epsilon \leq \sigma_0(x) \leq 1 + \epsilon$
- Anomaly with some minimal contrast to background, e.g., $\sigma(x) = \sigma_0(x) + \kappa(x)\chi_D, \quad \kappa(x) \ge 1$
- Can we rigorously guarantee to find inclusion D?

H./Ullrich: Monotonicity-based Rigorous Resolution Guarantee

- If $D = \emptyset$, methods return \emptyset .
- If $D \supset \omega_i$ then it is detected.

(Here: 32 electrodes, $\epsilon = 1\%$, $\delta = 1.4\%$)





Conclusions

Using monotonicity and localized potentials we showed that

- Uniqueness results for *piecewiese smooth* parameters may significantly differ from that for *globally smooth* ones.
- ▶ In shape reconstruction problems we can avoid non-linearity.
- Resolution guarantees for locating anomalies in unknown backgrounds with realistic finite precision data are possible.

Major limitations / open problems for our approach

- Piecewise analyticity required to prevent infinite oscillations.
- ► Voltage has to be measured on current-driven electrodes.